

Exact conservation laws for truncated gyrokinetic Vlasov-Poisson equations

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Exact conservation laws for the gyrokinetic Vlasov-Poisson equations can either be derived from a variational principle by the Noether method [1] or directly if exact invariants for gyrocenter Hamiltonian dynamics are known [2]. We begin our Noether derivation with the non-canonical gyrocenter phase-space Lagrangian

$$\Gamma_{\text{gy}} \equiv \left[\left(\frac{e}{c} \mathbf{A} + p_{\parallel} \hat{\mathbf{b}} \right) \cdot d\mathbf{X} - W dt \right] - (H_{\text{gy}} - W) d\tau, \quad (1)$$

where W is the extended phase-space energy coordinate and the gyrocenter Hamiltonian is

$$H_{\text{gy}}(\mathbf{X}, p_{\parallel}, \mu, t; \Phi_1) \equiv \mu B + \frac{p_{\parallel}^2}{2m} + \varepsilon e \langle \Phi_{1\text{gc}} \rangle. \quad (2)$$

The gyrocenter Euler-Lagrange equation associated with an arbitrary displacement $\delta\mathbf{X}$ is

$$\frac{e}{c} \frac{d_{\text{gy}}\mathbf{X}}{dt} \times \mathbf{B}^* - \frac{d_{\text{gy}}p_{\parallel}}{dt} \hat{\mathbf{b}} - \nabla H_{\text{gy}} = 0, \quad (3)$$

where $\mathbf{B}^* \equiv \mathbf{B} + (p_{\parallel}c/e) \nabla \times \hat{\mathbf{b}}$ and the gyrocenter canonical momentum is $\mathbf{p}_{\text{gy}} \equiv (e/c)\mathbf{A} + p_{\parallel} \hat{\mathbf{b}} \equiv (e/c)\mathbf{A}^*$, from which we obtain the Hamilton equation for the canonical momentum [1]

$$\frac{d_{\text{gy}}\mathbf{p}_{\text{gy}}}{dt} = -\nabla H_{\text{gy}} + \frac{e}{c} \nabla \mathbf{A}^* \cdot \frac{d_{\text{gy}}\mathbf{X}}{dt}. \quad (4)$$

In axisymmetric tokamak geometry, the magnetic vector potential is $\mathbf{A} \equiv -\psi \nabla \varphi + \Psi(\psi) \nabla \vartheta$, so that the magnetic field $\mathbf{B} \equiv \nabla \varphi \times \nabla \psi + q(\psi) \nabla \psi \times \nabla \vartheta$ yields the identity $\nabla \psi \equiv \mathbf{B} \times \partial \mathbf{X} / \partial \varphi$.

We now derive the Hamilton equation for the toroidal canonical gyrocenter momentum

$$p_{\text{gy}\varphi} \equiv \frac{\partial \mathbf{X}}{\partial \varphi} \cdot \mathbf{p}_{\text{gy}} = -\frac{e}{c} \psi + p_{\parallel} b_{\varphi}, \quad (5)$$

where $b_{\varphi} \equiv \hat{\mathbf{b}} \cdot \partial \mathbf{x} / \partial \varphi$ denotes the covariant toroidal component of the magnetic unit vector. By taking the toroidal projection of the gyrocenter Euler-Lagrange equation (3), we obtain [1] $d_{\text{gy}}p_{\text{gy}\varphi}/dt \equiv -\partial H_{\text{gy}}/\partial \varphi$, where we used the identity

$$\frac{\partial \mathbf{C}}{\partial \varphi} + \nabla \left(\frac{\partial \mathbf{x}}{\partial \varphi} \right) \cdot \mathbf{C} = \frac{\partial \mathbf{C}}{\partial \varphi} + \mathbf{C} \times \hat{\mathbf{z}} \equiv 0, \quad (6)$$

which is valid for an arbitrary vector field \mathbf{C} in axisymmetric tokamak geometry.

The truncated gyrokinetic Vlasov-Poisson equations are derived from the action functional

$$\mathcal{A}_{\text{gy}} = \int_{x^4} \left(\frac{\varepsilon^2 |\mathbf{E}_1|^2}{8\pi} - \frac{|\mathbf{B}|^2}{8\pi} \right) + \frac{\varepsilon^2}{2} \int_{z^7} F_0 e \langle \mathcal{L}_1 \Phi_{1\text{gc}} \rangle - \int_{Z^8} \mathcal{F}_{\text{gy}}(Z) \mathcal{H}_{\text{gy}}(Z; \Phi_1), \quad (7)$$

where summation over particle species is implied, with the extended gyrocenter Hamiltonian $\mathcal{H}_{\text{gy}} \equiv H_{\text{gy}} - W$ and the extended gyrocenter Vlasov distribution $\mathcal{F}_{\text{gy}} \equiv c \delta(W - H_{\text{gy}}) F$. In (7), the gyrocenter Lie derivative is $\mathcal{L}_1 \Phi_{1\text{gc}} \equiv (e/\Omega) \{ \tilde{\Phi}_{1\text{gc}}, \Phi_{1\text{gc}} \}_{\text{gc}}$, where $\tilde{\Phi}_{1\text{gc}} \equiv \int \tilde{\phi}_{1\text{gc}} d\theta$ and $\{ , \}_{\text{gc}}$ is the guiding-center Poisson bracket. The gyrokinetic variational principle $\delta \mathcal{A}_{\text{gy}} \equiv \int \delta \mathcal{L}_{\text{gy}} d^4x = 0$ introduces the variation of the gyrokinetic Lagrangian density

$$\delta \mathcal{L}_{\text{gy}} = -\varepsilon \delta \Phi_1 \left[e \int_{z^6} \left(\langle \delta_{\text{gc}}^3 \rangle F - \varepsilon F_0 \langle \mathcal{L}_1 \delta_{\text{gc}}^3 \rangle \right) \right] + \frac{\varepsilon^2}{4\pi} (\delta \mathbf{E}_1 \cdot \mathbf{E}_1) - \int \delta \mathcal{F}_{\text{gy}} \mathcal{H}_{\text{gy}} d^4p, \quad (8)$$

where $\delta \mathcal{F}_{\text{gy}} \equiv \{ \mathcal{S}_{\text{gy}}, \mathcal{F}_{\text{gy}} \}_{\text{gc}}$ is generated by the canonical generating function \mathcal{S}_{gy} and $\delta \mathbf{E}_1 \equiv -\nabla \delta \Phi_1$. From the variational principle, we obtain the gyrokinetic extended Vlasov equation $\{ \mathcal{F}_{\text{gy}}, \mathcal{H}_{\text{gy}} \}_{\text{gc}} = 0$, which, when integrated over W , yields the gyrocenter Vlasov equation [1]

$$\frac{\partial F}{\partial t} + \frac{d_{\text{gy}} \mathbf{X}}{dt} \cdot \nabla F + \frac{d_{\text{gy}} p_{\parallel}}{dt} \frac{\partial F}{\partial p_{\parallel}} = 0. \quad (9)$$

We also obtain the gyrokinetic Poisson equation

$$\frac{\varepsilon \nabla \cdot \mathbf{E}_1}{4\pi} = e \int_{z^6} \left(F \langle \delta_{\text{gc}}^3 \rangle - \varepsilon F_0 \langle \mathcal{L}_1 \delta_{\text{gc}}^3 \rangle \right) \equiv \rho - \nabla \cdot \mathbb{P}, \quad (10)$$

where ρ denotes the gyrocenter charge density and the gyrokinetic polarization

$$\mathbb{P} = \frac{\hat{\mathbf{b}}}{\Omega} \times \left[\int F \left(e \frac{d_{\text{gy}} \mathbf{X}}{dt} \right) d^3p \right] \equiv \mathbb{P}_{\text{gc}} + \mathbb{P}_{\text{gy}} \quad (11)$$

includes contributions from the guiding-center polarization (from the guiding-center velocity $d_{\text{gc}} \mathbf{X}/dt$) and the gyrocenter polatization (from the perturbed $E \times B$ velocity $\varepsilon (\hat{\mathbf{c}} \hat{\mathbf{b}}/B) \times \nabla \langle \Phi_{1\text{gc}} \rangle$).

By inserting (9)-(10) into (8), we obtain the gyrokinetic Noether equation $\delta \mathcal{L}_{\text{gy}} \equiv \partial \Lambda / \partial t + \nabla \cdot \Gamma$, where the Noether fields are

$$\Lambda \equiv \int \mathcal{S}_{\text{gy}} \mathcal{F}_{\text{gy}} d^4p \quad \text{and} \quad \Gamma \equiv -\frac{\varepsilon^2 \delta \Phi_1}{4\pi} \mathbf{E}_1 + \int \left(\mathcal{S}_{\text{gy}} \mathcal{F}_{\text{gy}} \right) \frac{d_{\text{gy}} \mathbf{X}}{dt} d^4p. \quad (12)$$

The gyrokinetic Noether equation is now used to derive the gyrokinetic toroidal angular-momentum conservation law. First, when considering arbitrary infinitesimal displacements $\delta \mathbf{x}$, we obtain the Noether momentum equation [1]

$$\frac{\partial \mathbf{P}}{\partial t} + \nabla \cdot \Pi_{\text{gy}} = - \int F \left(\nabla H_{\text{gy}} - \frac{e}{c} \nabla \mathbf{A}^* \cdot \frac{d_{\text{gy}} \mathbf{X}}{dt} \right), \quad (13)$$

where

$$\mathbf{P} = \int F \mathbf{p}_{\text{gy}} d^3p \quad \text{and} \quad \Pi_{\text{gy}} = \int F \frac{d_{\text{gy}} \mathbf{X}}{dt} \mathbf{p}_{\text{gy}} d^3p. \quad (14)$$

We note that (13) can also be obtained as the gyrocenter-Vlasov moment of (4). Second, we consider the infinitesimal toroidal rotation $\delta \mathbf{x} \equiv \delta \varphi \partial \mathbf{x} / \partial \varphi = \delta \varphi \hat{\mathbf{z}} \times \mathbf{x}$. The toroidal projection of (13) yields the gyrokinetic toroidal angular-momentum equation [1, 2]

$$\frac{\partial P_\varphi}{\partial t} + \nabla \cdot \mathbf{Q}_\varphi = -\varepsilon e \int F \frac{\partial \langle \Phi_{1gc} \rangle}{\partial \varphi} d^3 p, \quad (15)$$

where

$$P_\varphi \equiv \mathbf{P} \cdot \frac{\partial \mathbf{x}}{\partial \varphi} = \int F p_{gy\varphi} d^3 p \quad \text{and} \quad \mathbf{Q}_\varphi \equiv \Pi_{gy} \cdot \frac{\partial \mathbf{x}}{\partial \varphi} = \int F \frac{d_{gy} \mathbf{X}}{dt} p_{gy\varphi} d^3 p,$$

and we used the identity (6) to obtain

$$(\nabla \cdot \Pi_{gy}) \cdot \frac{\partial \mathbf{x}}{\partial \varphi} = \nabla \cdot \left(\Pi_{gy} \cdot \frac{\partial \mathbf{x}}{\partial \varphi} \right) - \Pi_{gy}^\top : \nabla \left(\frac{\partial \mathbf{x}}{\partial \varphi} \right) = \nabla \cdot \mathbf{Q}_\varphi + \int F \left(\frac{e}{c} \frac{\partial \mathbf{A}^*}{\partial \varphi} \cdot \frac{d_{gy} \mathbf{X}}{dt} \right).$$

Third, we introduce the operation of magnetic-surface average $\llbracket \cdots \rrbracket \equiv \mathcal{V}^{-1} \oint (\cdots) \mathcal{J} d\vartheta d\varphi$, with the magnetic-coordinate (ψ, θ, φ) Jacobian $\mathcal{J} \equiv (\nabla \psi \times \nabla \theta \cdot \nabla \varphi)^{-1}$ and $\mathcal{V} \equiv \oint \mathcal{J} d\vartheta d\varphi$. Next, we introduce the gyrokinetic parallel-toroidal momentum

$$P_{\parallel\varphi} \equiv P_\varphi + \frac{\psi}{c} \rho = \left(\int F p_{\parallel} d^3 p \right) b_\varphi, \quad (16)$$

and obtain the surface-averaged gyrokinetic parallel-toroidal momentum equation

$$\frac{\partial \llbracket P_{\parallel\varphi} \rrbracket}{\partial t} = -\frac{1}{\mathcal{V}} \frac{\partial}{\partial \psi} \left(\mathcal{V} \llbracket Q_\varphi^\psi \rrbracket \right) + \frac{\psi}{c} \frac{\partial \llbracket \rho \rrbracket}{\partial t} - \varepsilon e \left\llbracket \int F \frac{\partial \langle \Phi_{1gc} \rangle}{\partial \varphi} d^3 p \right\rrbracket, \quad (17)$$

where

$$\llbracket Q_\varphi^\psi \rrbracket = \left\llbracket \int F \frac{d_{gy} \psi}{dt} p_{gy\varphi} d^3 p \right\rrbracket \equiv \llbracket Q_{\parallel\varphi}^\psi \rrbracket - \frac{\psi}{c} \llbracket \nabla \psi \cdot \mathbf{J} \rrbracket,$$

and $\llbracket \nabla \psi \cdot \mathbf{J} \rrbracket \equiv e \left\llbracket \int F (d_{gy} \psi / dt) d^3 p \right\rrbracket$. Lastly, we use the gyrocenter charge conservation law

$$\frac{\partial \llbracket \rho \rrbracket}{\partial t} = -\llbracket \nabla \cdot \mathbf{J} \rrbracket \equiv -\frac{1}{\mathcal{V}} \frac{\partial}{\partial \psi} \left(\mathcal{V} \llbracket \nabla \psi \cdot \mathbf{J} \rrbracket \right), \quad (18)$$

so that (17) becomes

$$\frac{\partial \llbracket P_{\parallel\varphi} \rrbracket}{\partial t} = -\frac{1}{\mathcal{V}} \frac{\partial}{\partial \psi} \left(\mathcal{V} \llbracket Q_{\parallel\varphi}^\psi \rrbracket \right) + e \left\llbracket \int F \left(\frac{1}{c} \frac{d_{gy} \psi}{dt} - \varepsilon \frac{\partial \langle \Phi_{1gc} \rangle}{\partial \varphi} \right) d^3 p \right\rrbracket \quad (19)$$

where $c^{-1} d_{gy} \psi / dt - \varepsilon \partial \langle \Phi_{1gc} \rangle / \partial \varphi$ represents the gyrocenter toroidal electric field. If we now use the gyrokinetic quasineutrality condition $\rho \equiv \nabla \cdot \mathbb{P}$, the gyrocenter charge conservation law (18) becomes (with $\mathcal{P}^\psi \equiv \nabla \psi \cdot \mathbb{P}$)

$$\frac{\partial \llbracket \rho \rrbracket}{\partial t} \equiv \left\llbracket \nabla \cdot \frac{\partial \mathbb{P}}{\partial t} \right\rrbracket = \frac{1}{\mathcal{V}} \frac{\partial}{\partial \psi} \left(\mathcal{V} \frac{\partial \llbracket \mathcal{P}^\psi \rrbracket}{\partial t} \right)$$

which implies the gyrocenter ambipolarity condition $[[J_{\text{phys}}^\psi]] \equiv [(\partial \mathcal{P}^\psi / \partial t) + \nabla \psi \cdot \mathbf{J}] \equiv 0$, where the magnetization-current contribution vanishes since $[[\nabla \psi \cdot \nabla \times \mathbf{M}]] = [[\nabla \cdot (\mathbf{M} \times \nabla \psi)]] \equiv 0$. The parallel-toroidal momentum equation (19) thus becomes

$$\frac{\partial}{\partial t} \left([[P_{\parallel\varphi}]] + \frac{1}{c} [[\mathcal{P}^\psi]] \right) + \frac{1}{\mathcal{V}} \frac{\partial}{\partial \psi} \left(\mathcal{V} [[Q_{\parallel\varphi}^\psi]] \right) = -\varepsilon e \left[\int F \frac{\partial \langle \Phi_{1\text{gc}} \rangle}{\partial \varphi} d^3 p \right]. \quad (20)$$

Here, the total toroidal-momentum density $[[P_{\parallel\varphi}]] + c^{-1} [[\mathcal{P}^\psi]]$ is derived from the gyrocenter Vlasov moment of the toroidal gyrocenter velocity

$$\frac{\partial \mathbf{X}}{\partial \varphi} \cdot m \frac{d_{\text{gy}} \mathbf{X}}{dt} \equiv m R^2 \frac{d_{\text{gy}} \varphi}{dt} = p_{\parallel} b_{\varphi} - \frac{\nabla \psi}{B\Omega} \cdot \left(\mu \nabla B + \frac{p_{\parallel}^2}{m} \hat{\mathbf{b}} \cdot \nabla \hat{\mathbf{b}} + \varepsilon e \nabla \langle \Phi_{1\text{gc}} \rangle \right),$$

where the first term contributes to $[[P_{\parallel\varphi}]]$ while the second set of terms contribute to the radial gyrokinetic polarization $[[\mathcal{P}^\psi]] \equiv [[\mathcal{P}_{\text{gc}}^\psi]] + \varepsilon [[\mathcal{P}_{\text{gy}}^\psi]]$. As our last step, we perform a guiding-center multipole expansion: $\partial \langle \Phi_{1\text{gc}} \rangle / \partial \varphi \equiv \partial \Phi_1 / \partial \varphi + \langle \rho_{\text{gc}} \rangle \cdot \nabla (\partial \Phi_1 / \partial \varphi) + \dots$ so that we find

$$e \int F \frac{\partial \langle \Phi_{1\text{gc}} \rangle}{\partial \varphi} d^3 p \simeq (\rho_{\text{gy}} - \nabla \cdot \mathbb{P}_{\text{gc}}) \frac{\partial \Phi_1}{\partial \varphi} + \nabla \cdot \left(\mathbb{P}_{\text{gc}} \frac{\partial \Phi_1}{\partial \varphi} \right) = \varepsilon (\nabla \cdot \mathbb{P}_{\text{gy}}) \frac{\partial \Phi_1}{\partial \varphi} + \nabla \cdot \left(\mathbb{P}_{\text{gc}} \frac{\partial \Phi_1}{\partial \varphi} \right),$$

where we used the gyrokinetic quasineutrality condition $\rho_{\text{gy}} - \nabla \cdot \mathbb{P}_{\text{gc}} = \varepsilon \nabla \cdot \mathbb{P}_{\text{gy}}$. Hence, the parallel-toroidal momentum equation (20) becomes

$$\frac{\partial}{\partial t} \left[P_{\parallel\varphi} + \frac{1}{c} \mathcal{P}^\psi \right] = -\frac{1}{\mathcal{V}} \frac{\partial}{\partial \psi} \left(\mathcal{V} \left[Q_{\parallel\varphi}^\psi + \varepsilon \mathcal{P}_{\text{gc}}^\psi \frac{\partial \Phi_1}{\partial \varphi} \right] \right) - \varepsilon^2 \left[(\nabla \cdot \mathbb{P}_{\text{gy}}) \frac{\partial \Phi_1}{\partial \varphi} \right]. \quad (21)$$

We note that, in the zero-Larmor-radius approximation $\mathbb{P}_{\text{gy}} \simeq (mnc^2/B^2) \nabla_{\perp} \Phi_1$, we find

$$\left[(\nabla \cdot \mathbb{P}_{\text{gy}}) \frac{\partial \Phi_1}{\partial \varphi} \right] \simeq \left[\nabla \cdot \left(\mathbb{P}_{\text{gy}} \frac{\partial \Phi_1}{\partial \varphi} \right) - \frac{\partial}{\partial \varphi} \left(\frac{mnc^2}{2B^2} |\nabla_{\perp} \Phi_1|^2 \right) \right] = \frac{1}{\mathcal{V}} \frac{\partial}{\partial \psi} \left(\mathcal{V} \left[\mathcal{P}_{\text{gy}}^\psi \frac{\partial \Phi_1}{\partial \varphi} \right] \right),$$

so that (21) becomes the gyrokinetic toroidal angular-momentum conservation law for the truncated gyrokinetic Vlasov-Poisson equations (compare with equation 98 of [2])

$$\frac{\partial}{\partial t} \left[P_{\parallel\varphi} + \frac{1}{c} \mathcal{P}^\psi \right] = -\frac{1}{\mathcal{V}} \frac{\partial}{\partial \psi} \left(\mathcal{V} \left[Q_{\parallel\varphi}^\psi + \varepsilon \mathcal{P}^\psi \frac{\partial \Phi_1}{\partial \varphi} \right] \right), \quad (22)$$

which includes guiding-center and gyrocenter polarization effects.

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References

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