

# Scaling laws of the plasma velocity in visco-resistive magnetohydrodynamic systems

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## Abstract

We consider a visco-resistive magnetohydrodynamic modeling of a steady-state incompressible tokamak plasma with a prescribed toroidal current drive, featuring constant resistivity  $\eta$  and viscosity  $\nu$ . We reintroduce in the traditional Grad-Shafranov equation the dissipative viscous term and the non-linear  $(\mathbf{v} \cdot \nabla)\mathbf{v}$  term coming from the steady-state Navier-Stokes equation [1, 2, 3, 4, 5, 6]. It is shown that the plasma velocity root-mean-square behaves as  $\eta f(H)$  as long as the inertial term remains negligible, where  $H$  stands for the Hartmann number  $H \equiv (\eta\nu)^{-1/2}$ , and that  $f(H)$  exhibits power-law behaviours in the limits  $H \ll 1$  and  $H \gg 1$ . In the latter limit, we establish that  $f(H)$  scales as  $H^{1/4}$ , which is consistent with numerical results. These use the finite element method through the open-source platform FreeFem++ for solving partial differential equations [7].

## Behaviour of the plasma velocity

The computation of visco-resistive axisymmetric steady states involves solving the steady-state incompressible Navier–Stokes equation (1)-(2) along with the solenoidal condition (3), Faraday’s law (4), Ampère law (5) and Ohm’s law (6)

$$(\mathbf{v} \cdot \nabla)\mathbf{v} = \mathbf{J} \times \mathbf{B} - \nabla p + \nu \nabla^2 \mathbf{v}, \quad (1)$$

$$\nabla \cdot \mathbf{v} = 0, \quad (2)$$

$$\nabla \cdot \mathbf{B} = 0, \quad (3)$$

$$\nabla \times \mathbf{E} = 0, \quad (4)$$

$$\nabla \times \mathbf{B} = \mathbf{J}, \quad (5)$$

$$\mathbf{E} + \mathbf{v} \times \mathbf{B} = \eta \mathbf{J}. \quad (6)$$

on a tokamak poloidal plasma cross-section  $\Omega$ . Let  $E_0$  be the toroidal electric field. In the present study, we are interested in the behavior of the system for a given ratio of  $E_0/\eta$ . This quantity may be viewed as the only explicit drive appearing in the dimensionless system of

equations. Combining the Navier-Stokes equation and Ohm's law yields

$$\boldsymbol{\omega} \times \mathbf{v} = -\nabla p^* + \left( \frac{\mathbf{E}}{\eta} + \eta^{-1} \mathbf{v} \times \mathbf{b} \right) \times \mathbf{b} + \nu \nabla^2 \mathbf{v}. \quad (7)$$

Using the Hartmann number,  $H$ , defined as  $H = (\eta\nu)^{-1/2}$ , this reads and introducing  $\mathbf{v} = (\eta/\nu)^{1/2} \tilde{\mathbf{v}}$ :

$$\eta^2 H^2 \tilde{\boldsymbol{\omega}} \times \tilde{\mathbf{v}} = -\nabla p^* + \left( \frac{\mathbf{E}}{\eta} + H \tilde{\mathbf{v}} \times \mathbf{b} \right) \times \mathbf{b} + H^{-1} \nabla^2 \tilde{\mathbf{v}}. \quad (8)$$

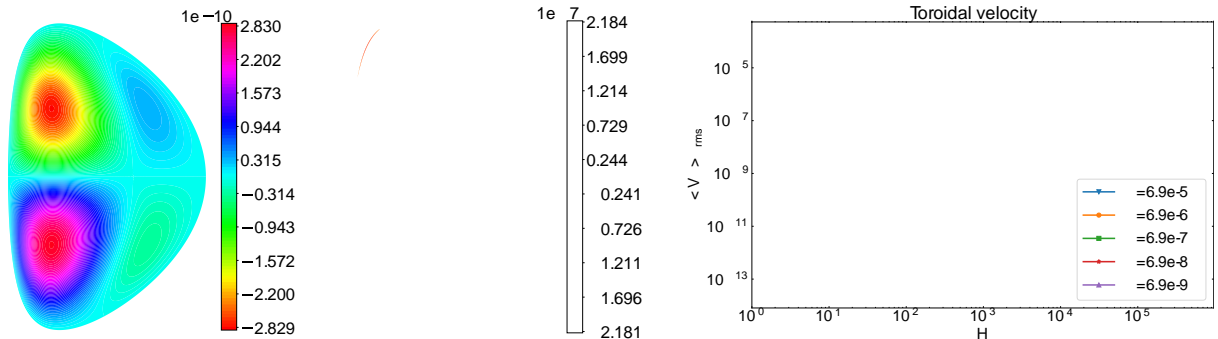
If we neglect inertial term and eliminate pressure by taking the curl of the equation then we are left with

$$\nabla \times \left[ \left( \frac{\mathbf{E}}{\eta} + H \tilde{\mathbf{v}} \times \mathbf{b} \right) \times \mathbf{b} + H^{-1} \nabla^2 \tilde{\mathbf{v}} \right] = \mathbf{0} \quad (9)$$

and, at given  $\mathbf{E}/\eta$ , plasma velocity  $\tilde{\mathbf{v}}$  must be a function of  $H$  only, meaning that  $\mathbf{v}/\eta = H \tilde{\mathbf{v}}$  is a function of  $H$  only. This prevalence of the Hartmann number was already inferred in the Reverse Field Pinch [8] where visco-resistive MHD simulations showed that the transition from multiple to quasi-single helicity states is controlled by the Hartmann number.

## Numerical results

Fig. 1 on the left depicts the computed steady-state toroidal velocity fields for two different Hartmann numbers:  $H = 10$  and  $H = 10^5$  at a given resistivity  $\eta$ .



**Figure 1:** (On the left) Toroidal velocity field for  $H = 10$  and  $H = 10^5$  with  $\eta=6.9\text{e-}9$  and  $E_0/\eta = 0.43$ . (On the right) Root-mean square of the toroidal velocity field in Alfvén velocity units as a function of the Hartmann number in log-log scale for different values of the resistivity with  $E_0/\eta = 0.43$ .

The log-log plot of Fig. 1 on the right demonstrate that, at a given  $E_0/\eta$  ratio, the velocity is proportional to the resistivity and to some function depending solely on the Hartmann number.

## Scaling Laws

The scaling of velocity in the first regime where  $H \ll 1$  was predicted analytically [2]. The toroidal velocity in this limit scales with  $H^4$  while the poloidal velocity scales with  $H^2$ . We analytically predict the velocity behaviour in  $H \gg 1$  regime by considering the boundary layer equations [9]. This gives the boundary layer thickness scaling as  $\delta \sim \frac{1}{\sqrt{H}}$ . Consequently,  $\langle \tilde{v}_\phi \rangle_{rms} \sim H/\eta \delta^{-1/2}$ , so that in the original velocity variable and using boundary layer